

Multi Frequency Synthesis Imaging with Wideband EVLA Data

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Atacama Large Millimeter/submillimeter Array
Expanded Very Large Array
Robert C. Byrd Green Bank Telescope
Very Long Baseline Array



Outline

- Continuum Imaging of wide-band (E)VLA data.
- Algorithms
 - multi-scale maps of continuum flux, spectral index and curvature
- Application to CygA and M87 data
 - taken with EVLA receivers and the VLA correlator
- Frequency-dependent Primary Beam correction
 - preliminary results

Data from wideband receivers

- Nearly continuous coverage across a wide band

=> increased sensitivity $I_{rms} \propto \frac{1}{\sqrt{\delta \nu}}$

- A large total frequency range

=> can measure spectral features.

For a Power Law Spectrum across a 2:1 bandwidth...

$$\alpha = -0.5, \quad \nu_{max} = 2\nu_{min}, \quad \nu_0 = 1.5\nu_{min}$$

Need SNR > 6 to measure spectral index

Need SNR > 100 to measure spectral curvature

Imaging with wideband data

At different frequency channels...

- UV coverage and angular resolution change

$$u = \frac{b}{\lambda} = \frac{b \nu}{c}$$

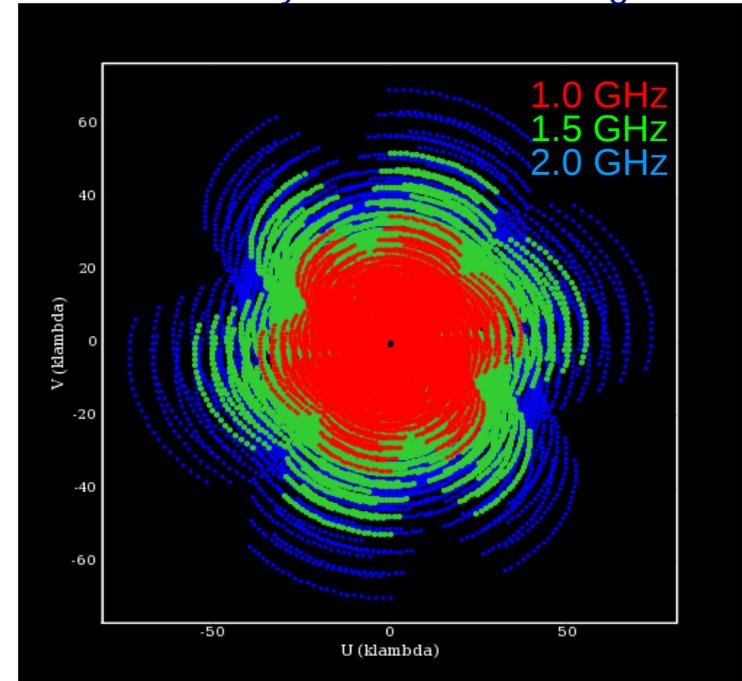
- Antenna field-of-view changes

$$fov = \frac{\lambda}{D} = \frac{c}{\nu D}$$

Combine all data :

- Higher Sensitivity
- Higher Angular Resolution
- Better Imaging Fidelity
- Wider Field of View

VLA C-Array L-Band uv-coverage



MFS : Multi-Frequency Synthesis Imaging

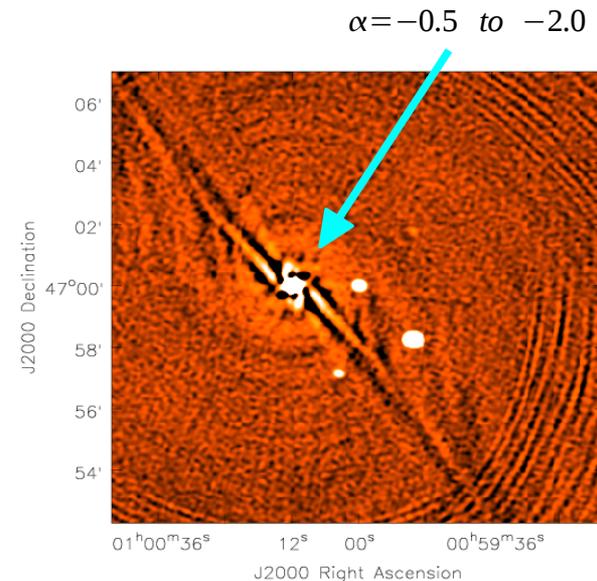
- Flat spectrum sources + Narrow field : Standard deconvolution algorithms
- With spectral structure :

Standard deconvolution with MFS will turn spectral features into spurious spatial structure.

Dynamic Range ~ 1000 for
 $\alpha = -1.0$ across 1 GHz at L-Band. (*Conway et al, 1990*)

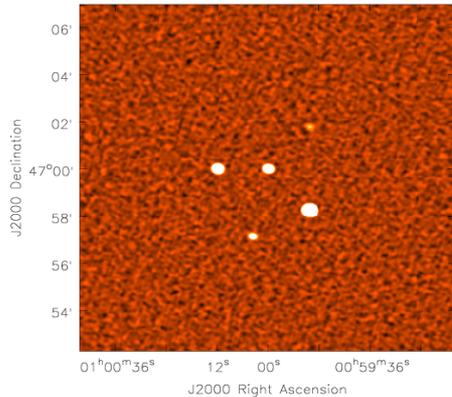
- Varying field-of-view :

Frequency-dependent Primary Beams will introduce spurious spectral structure for off-center sources.



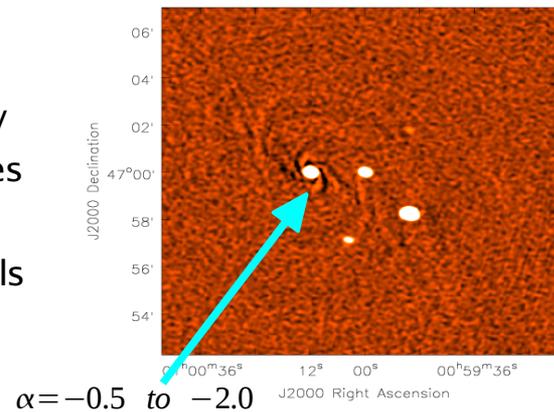
MFS for point sources

(A) Spectral Line Imaging



- Deconvolve each channel separately
- Combine all images
- Deconvolve on continuum residuals

(B) MFS with a spectral model



- MF-CLEAN
(Sault, Wieringa, 1994)
- Spectrum : Linear
- Flux : Point-Sources
- Output : Stokes I, Spectral Index

- Image Fidelity

(A) Single frequency uv-coverage

(B) Multi-Frequency uv-coverage

- Angular Resolution of Spectral Index/Curvature maps

(A) Lowest (u_{max} at v_{min})

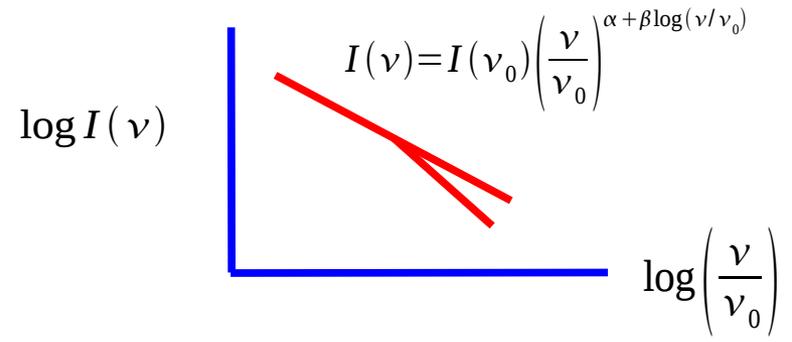
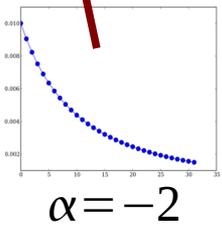
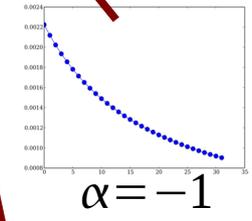
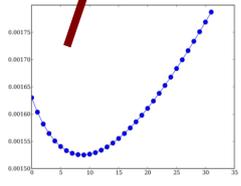
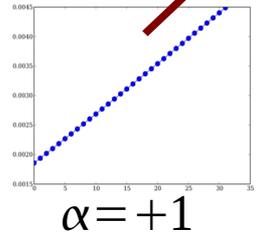
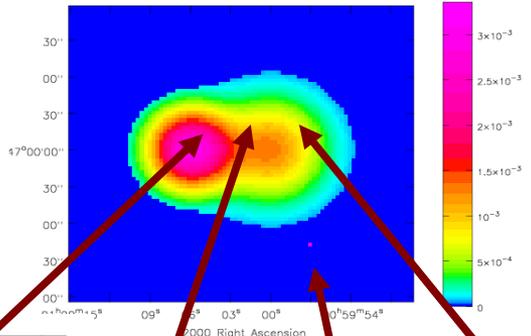
(B) Highest (u_{max} at v_{max})

... both (A) and (B) are not always suitable for extended emission.

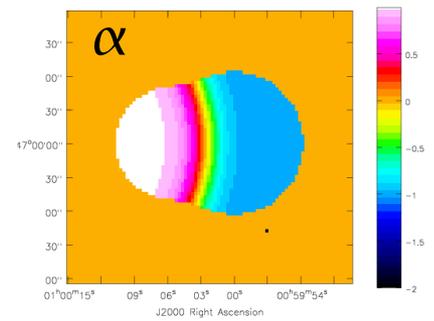
Multi-scale MFS

EVLA C-array simulation, 1-2 GHz.

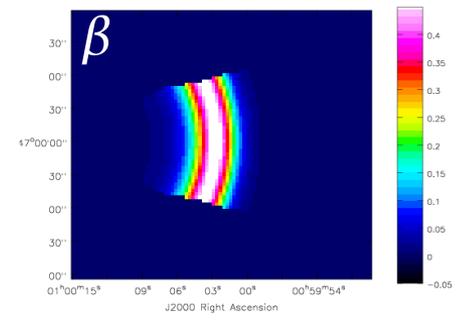
Image at Reference Frequency



Spectral Flux Model : Power Law with varying index



Average Spectral Index



Gradient in Spectral Index

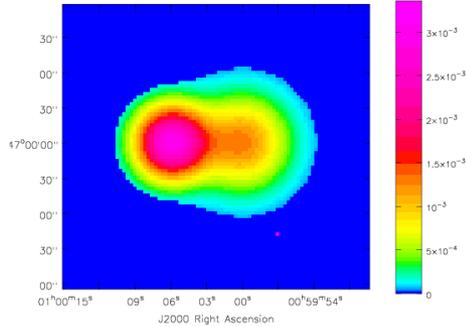
MS-MFS simulations

MFS

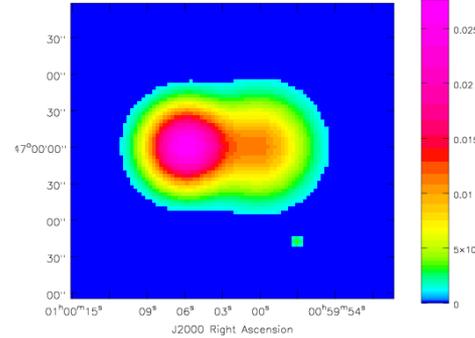
Image at reference frequency

$$I(\nu_0)$$

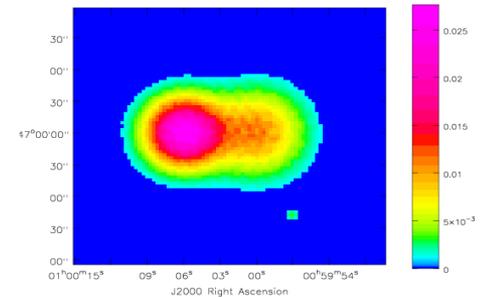
True Images



multi-scale

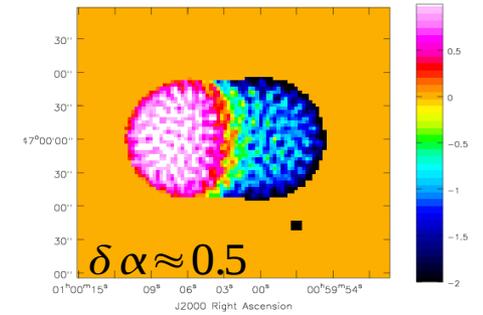
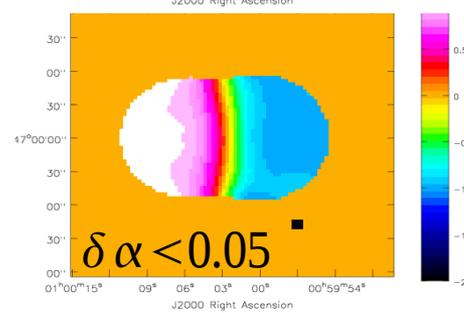
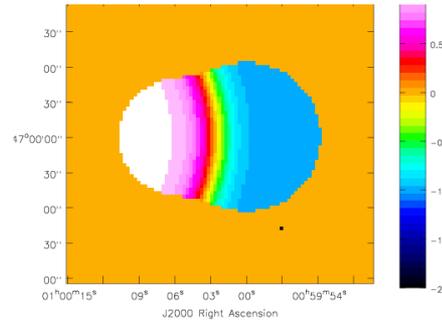


point-source



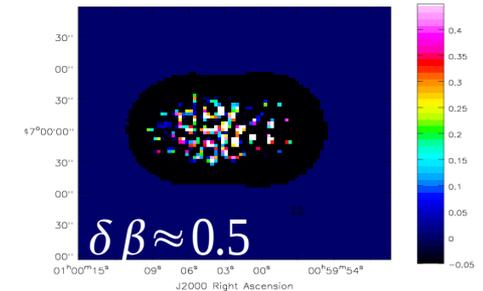
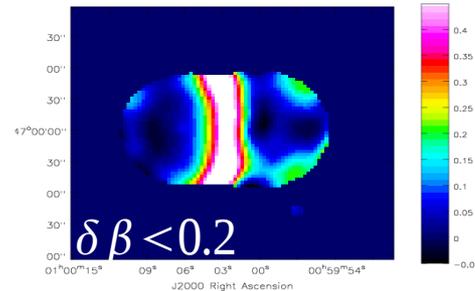
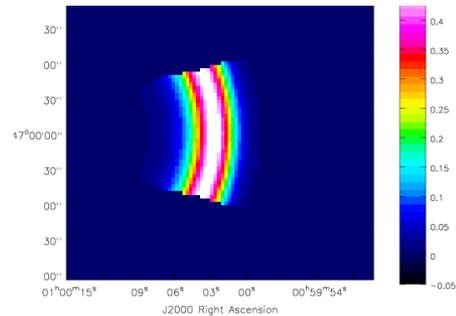
Average Spectral Index

$$\alpha$$

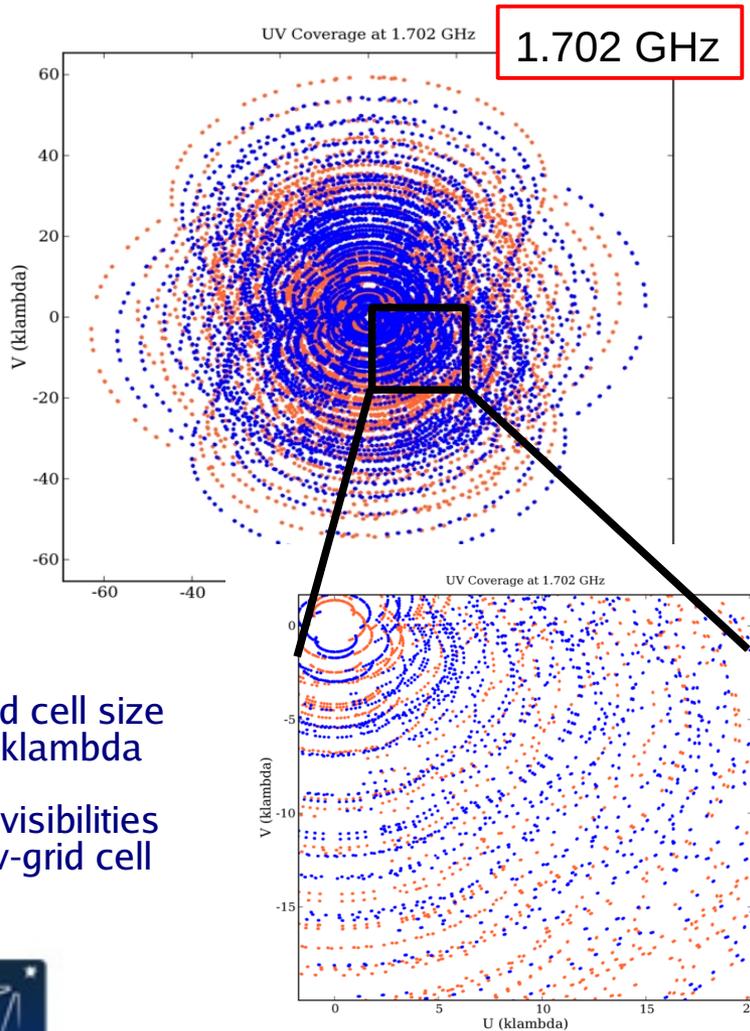


Gradient in Spectral Index

$$\beta$$

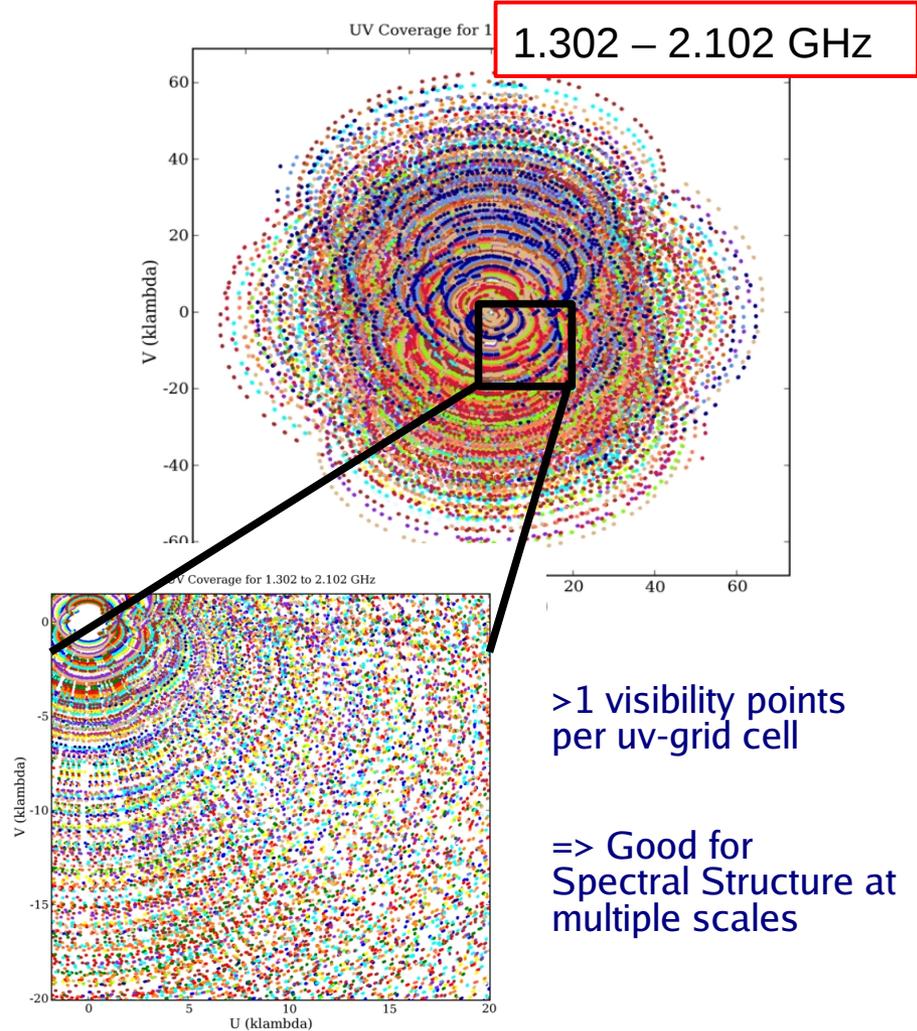


Synthesized wideband EVLA uv-coverage



uv-grid cell size
~ 0.2 klambda

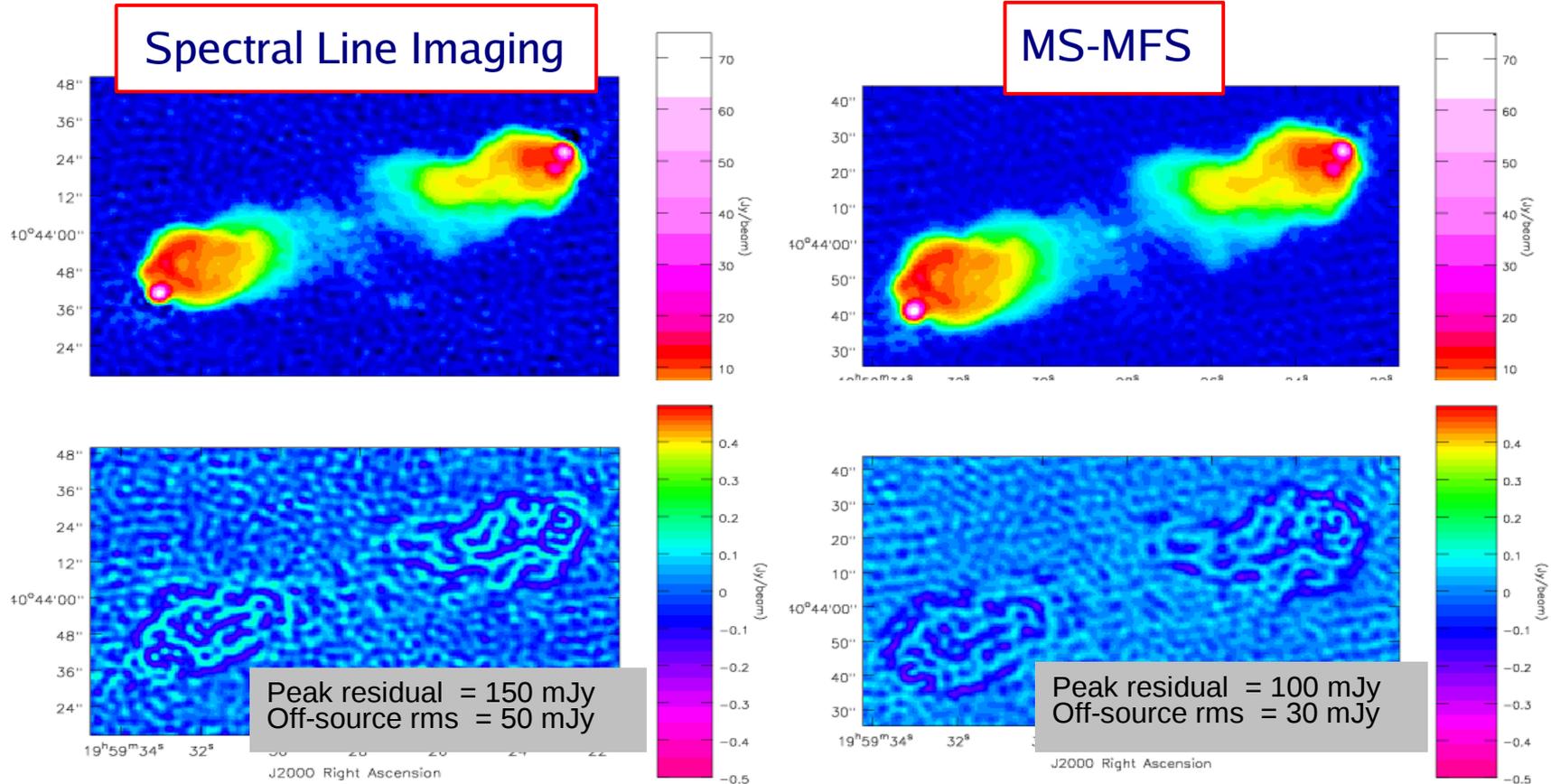
< 0.5 visibilities
per uv-grid cell



> 1 visibility points
per uv-grid cell

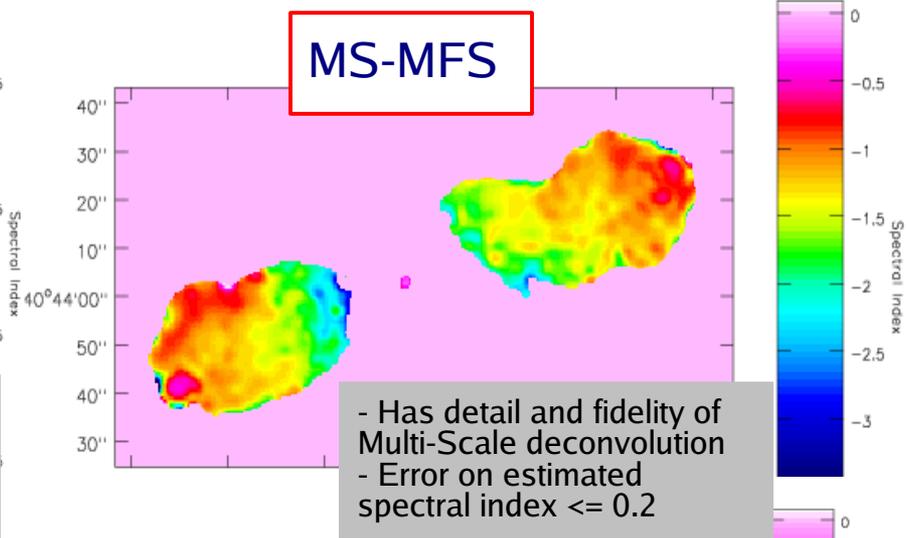
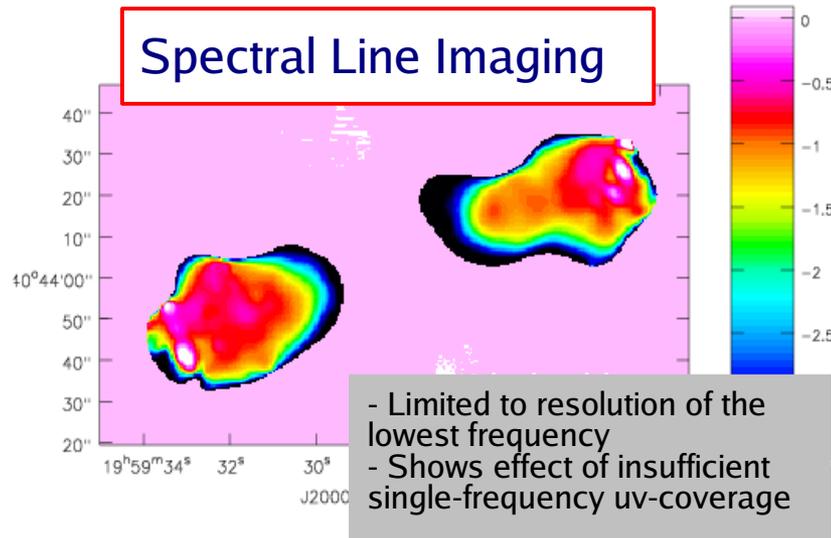
=> Good for
Spectral Structure at
multiple scales

CygA : Stokes I (images and residuals)



- both algorithms work well
- both have similar residual errors due to deconvolution.

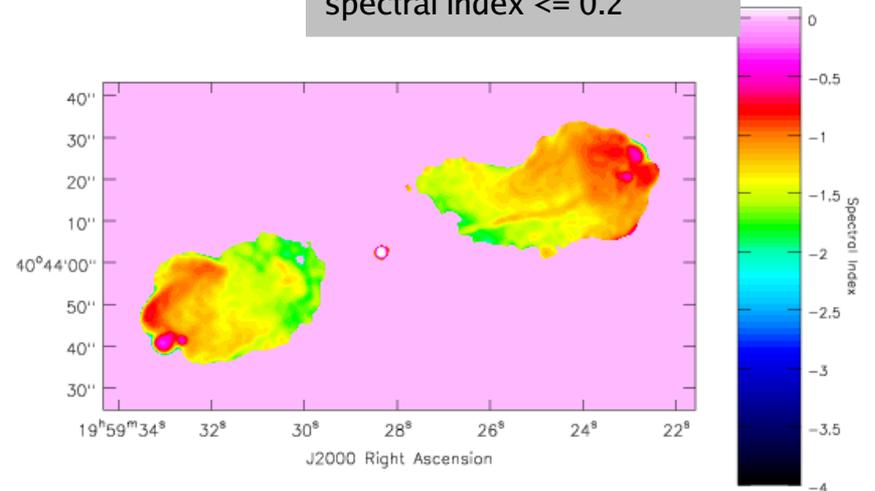
CygA : Spectral index



For comparison,

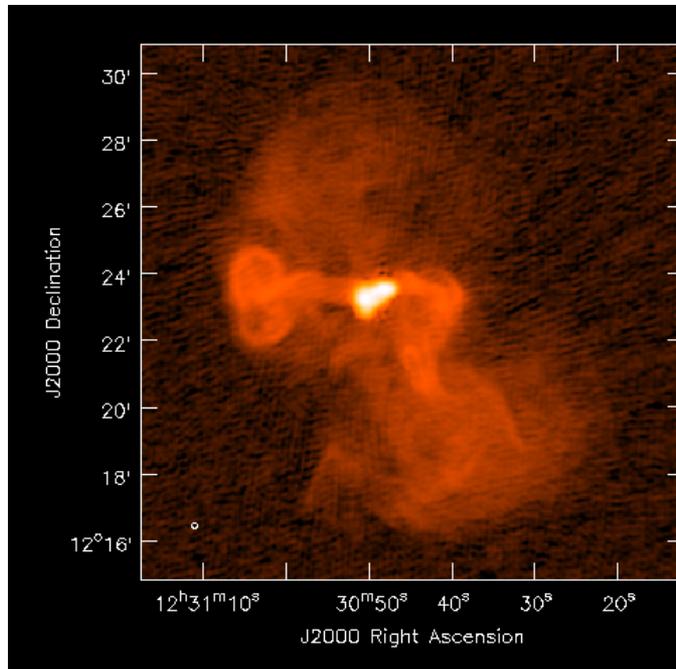
Spectral Index Map constructed from images at 1.4GHz and 4.8GHz, obtained from C.Carilli et al, Ap.J. 1991. (VLA A,B,C,D Array at L and C band)

Map has been smoothed to 1 arcsec.

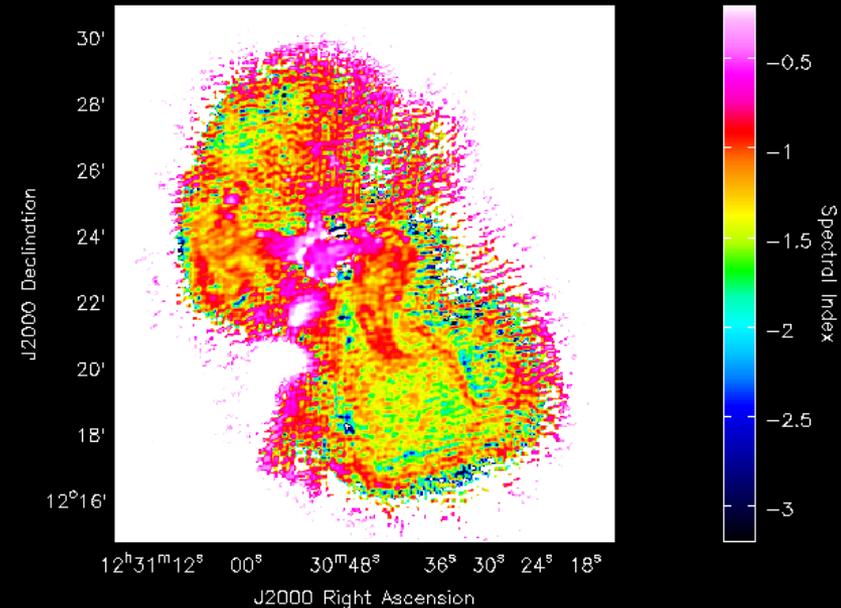


M87 : Stokes I , Spectral Index

Total Intensity Image

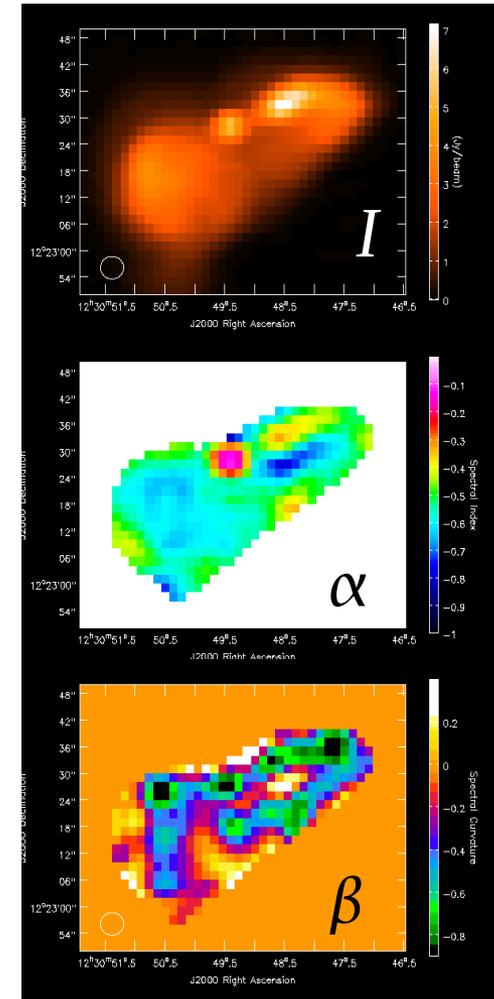
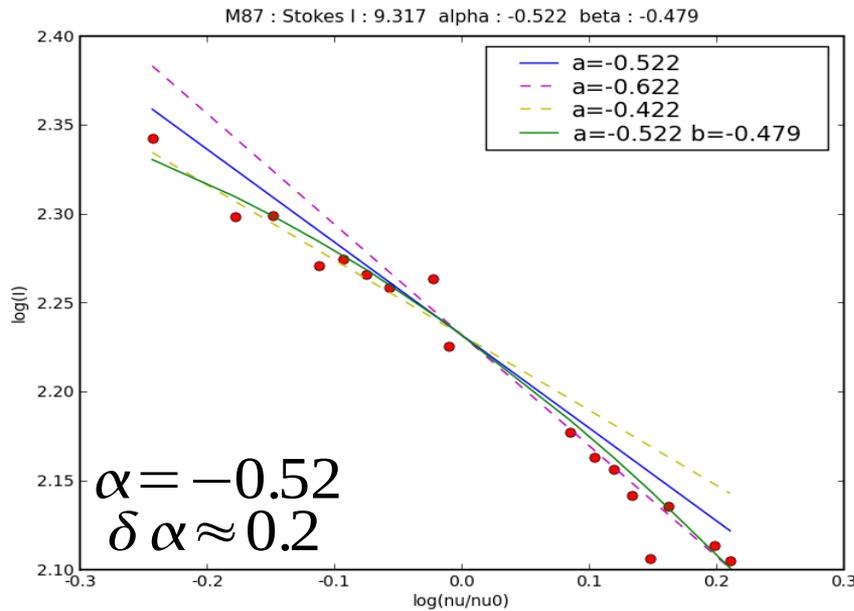


Spectral Index Map



VLA C-array : Cycle through 16 frequencies between 1.18 –1.86 GHz, 25MHz bands, RR,LL
~ 30 mins per frequency, spread across 10 hrs
=> 10 x 3min snapshots per frequency

M87 : Spectral Curvature (core+inner jet)

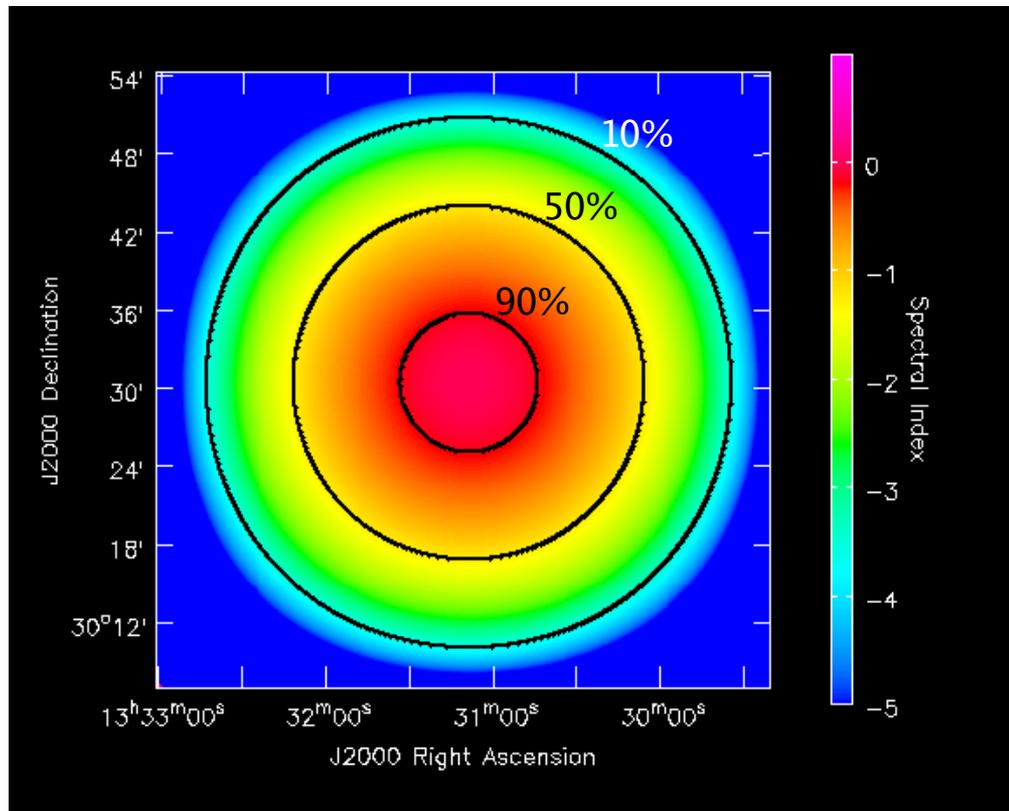


Points : from spectral line maps

Lines : from MS-MFS

- Need SNR > 100 to fit spectral variation ~ 0.2

Frequency dependant primary beam



Varying Field-Of-View :

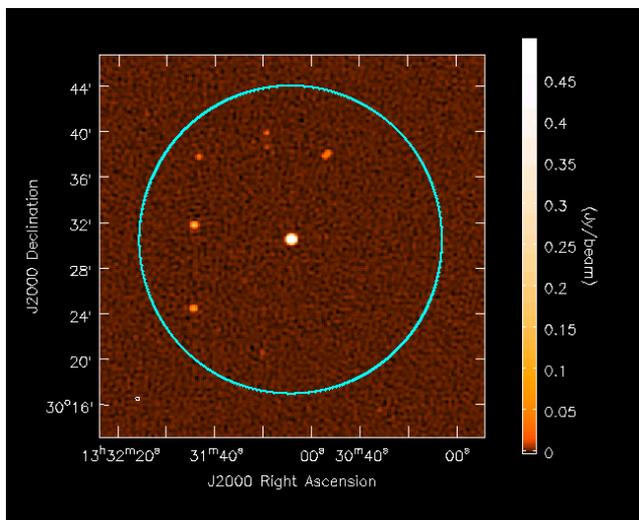
- Introduces a spurious spectral index
- Can be corrected during imaging and weighted by noise during deconvolution.

Contours : Average Primary Beam at 10%, 50% and 90% level.

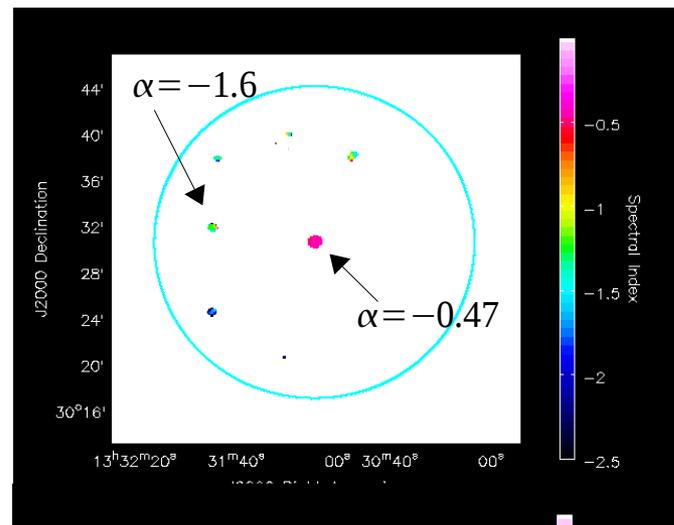
Colors : Spectral Index of the primary beam within the main lobe.

Frequency-dependent PB correction

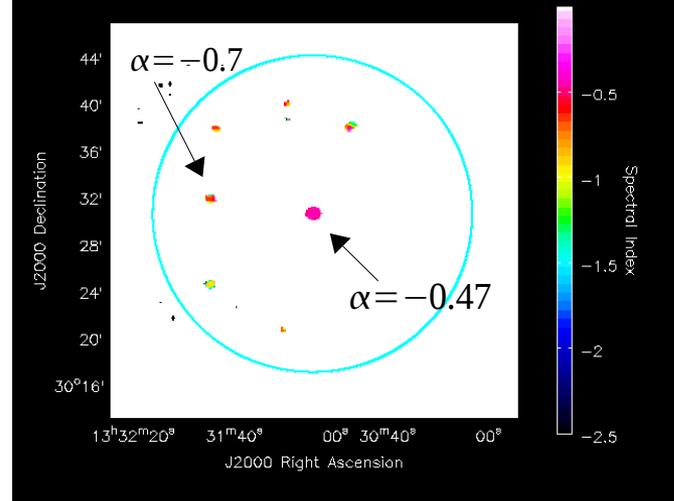
3C286 field (1.2 GHz to 1.8 GHz)



Without PB correction



With PB correction



Current error bar on the PB-corrected spectral index ~ 0.15

(from another observation of 3C147 at 40% of PB)

Computation/Performance

	Spectral-Line Imaging	MS-MFS
Number of deconvolution runs	N_{chan}	1
Data I/O per solver Major Cycle	$N_{\text{vis}} / N_{\text{chan}}$	N_{vis}
Memory Use per deconvolution run (multi-scale)	Image Size x N_{scales}^2	Image Size x $(N_{\text{taylor}} \times N_{\text{scales}})^2$
Runtime (for few GB of EVLA data on CygA, M87)	~ 30 hours parallelized : ~ 7.5 hours (theoretical –for 4 nodes)	~ 12 hours parallelized : ~ 4 hours (measured –on 4 nodes)

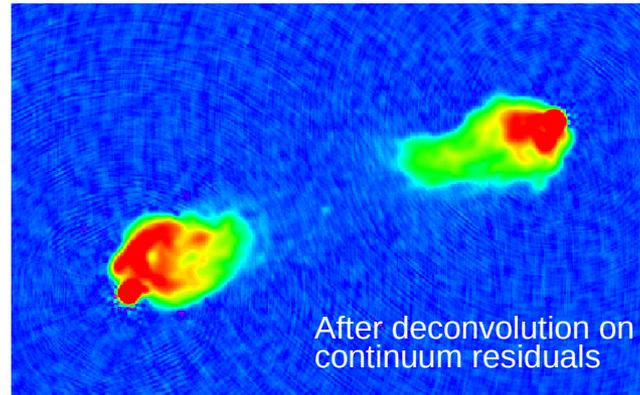
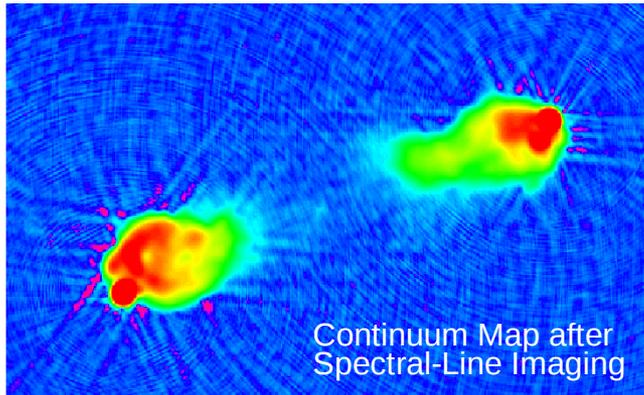
Trade-Off between source complexity, available uv-coverage, desired angular resolution of spectral index map, and algorithm simplicity/stability.

Summary

- Wide-Band receivers provide increased uv-coverage and sensitivity and measure spectra.
- Continuum Imaging :
 - Model both spatial and spectral structure (spectral index and curvature)
 - Correct for a frequency-dependent primary beam
- Point Sources : Algorithms can get to 10^6 dynamic range
- Extended Emission : Algorithms can get to $>10^5$ dynamic range
(limited by multiscale algorithms)
- Spectral Structure (for 2:1 bandwidth)
 - Need SNR > 6 to measure spectral index ~ 0.5
 - Need SNR > 50 to measure spectral index variation (curvature) ~ 0.2
- Work in progress : PB measurement (holography) across L-Band, modelling and correction during MFS deconvolution, and error analysis.

Hybrid Algorithm – extended emission

Spectral-Line Imaging + Deconvolution on continuum residuals



Cygnus-A⁺ simulation (40 channels, L-Band to C-Band, 4 hours) => Ideal data

Target dynamic range : 10^6
Target pt-source rms : 10 μ Jy

Max Dynamic range : 10^6
(component image)

Max Dynamic range : 10^5
(restored image)

Simple hybrid algorithm can handle arbitrary spectra and will suffice (upto calibration limits)

- for point sources
- for extended sources if there is sufficient uv-coverage per channel